Ryugu as observed by MASCOT: Preliminary Results of the MARA Instrument

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Wissen für Morgen

The FOVs of MARA in the Cam image, Plane 30 mm above the ground





Approximate field of view of MARA, steographic reconstruction of the 3D shape of the boulder is in progress

MARA During On-Asteroid Operations







Deep

Temperature Measurement Uncertainty



- Brightness temperatures have bee calibrated using all in-flight data during cruise as well as the deep space views during on-asteroid operations.
- The 8-12 µm filter was found to be the best performing filter
- In general, brightness temperature errors are <1 K during daytime, but grow large for the narrow bandpasses during nighttime.









Illumination Model

- The illumination model has been calculated based on the location of MASCOT at -22.30° N, 317.13° E
- The orientation of the observed surface with respect to the local landing site orientation is unknown
- Orientation of the surface normal is varied by $\pm 25^{\circ}$ around the nominal surface normal.
- Illumination is calculated by $I_{max} \cdot \vec{n}_{facet} \cdot \vec{v}_{sun}$
- Sunrise and sunset have been adapted to fit the GNC sensors and the temperature data







Thermal Inertia - Best Fit







- Data is fitted for nighttime temperatures after 11:00 UTC
- Excellent fit during nighttime
- Modelled daytime temperatures are higher than the observed ones
- This can be a roughness effect

Thermal Inertia - Roughness







- Roughness reduces the daytime fluxes for the MARA viewing geometries
- We use a simple roughness model using spherical cavities
- The model takes the viewing geometry into account but not vertical heat conduction

Thermal Inertia Estimate







 Besides the various possible surface orientations, emissivity was varied from 0.9 to 1 and thermal radiation from the was modeled or ignored

for each of the above cases thermal inertia is fitted to the data, shown are those combinations with a sufficiently low χ^2

Thermal Inertia Estimate







- The assumed emissivity has a small influence on the obtained results

Acceptable fits result in thermal inertia ranging from 247to 375 J m⁻² K⁻¹ s^{-1/2} with a best fit for 282 J m⁻² K⁻¹ s^{-1/2} and an emissivity of 1

Thermal Inertia Estimate







- Thermal radiation of the surrounding terrain will systematically increase temperatures throughout the day

 Assuming 8% view factor to surrounding, ambient temperature same as observed brightness temperature, retrieved thermal intertia decreases down to 247 J m⁻² K⁻¹ s^{-1/2}

Thermal Inertia Estimate







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Estimated thermal inertia range is a upper limit, stronger thermal radiation from the evironment would decrease the estimate

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Estimated Thermal Conductivity and Porosity







- Assuming a grain density typical for CI meteorites, $\rho_s = 2420 \text{ kg m}^{-3}$, and a model of c_p we derive thermal conductivity $k(\phi)$ from thermal inertia
 - Comparison to three models of thermal conductivity based on meteorite samples to derive thermal conductivity and porosity of Ryugu
 - Large gap in the data for C chondrites

Lab Work - Thermal Conductivity Measurement Setup







Coldfinger -150 to +50° C Sample Container

Transient Hot Strip

Summary and Conclusions





- MARA observed a full day-night at MASCOT site 2, looking at a boulder in its field of view
- The best fitting thermal inertia of the boulder as derived from nighttime data is 282⁺⁹³₋₃₅J K⁻¹ m⁻² s^{-1/2}
- The estimate will be refined considering thermal re-radiation, probably extending the lower errorbar
- Current TI estimates indicate a highly porous boulder with $\phi = 28 46\%$
- The low TI of small bodies may be unrelated to regolith cover. Rather, it could reflect the high porosity of surface boulders
- We still need thoroughly investigate re-radiation and roughness when more 3D data is available from MASCAM



